

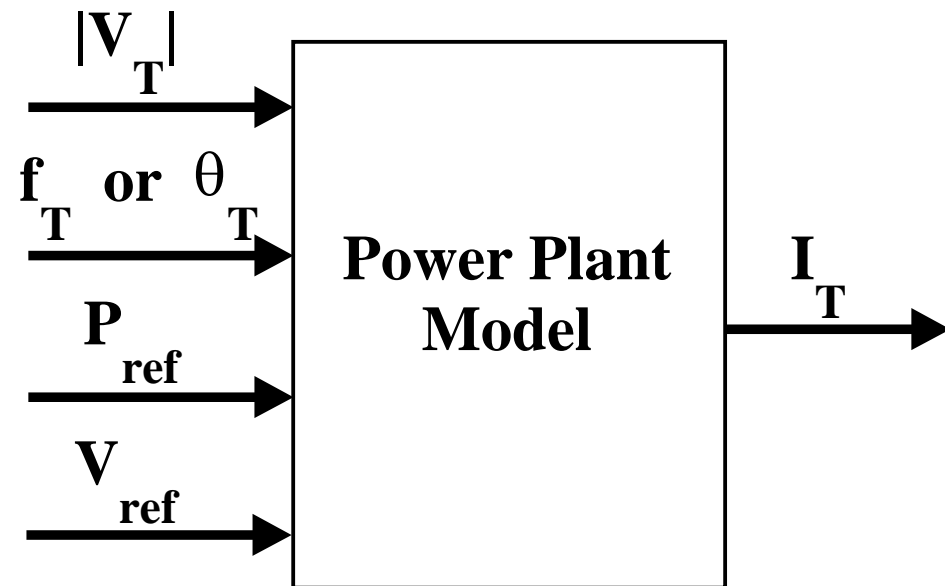
Input Estimation for Power Plant Model Validation

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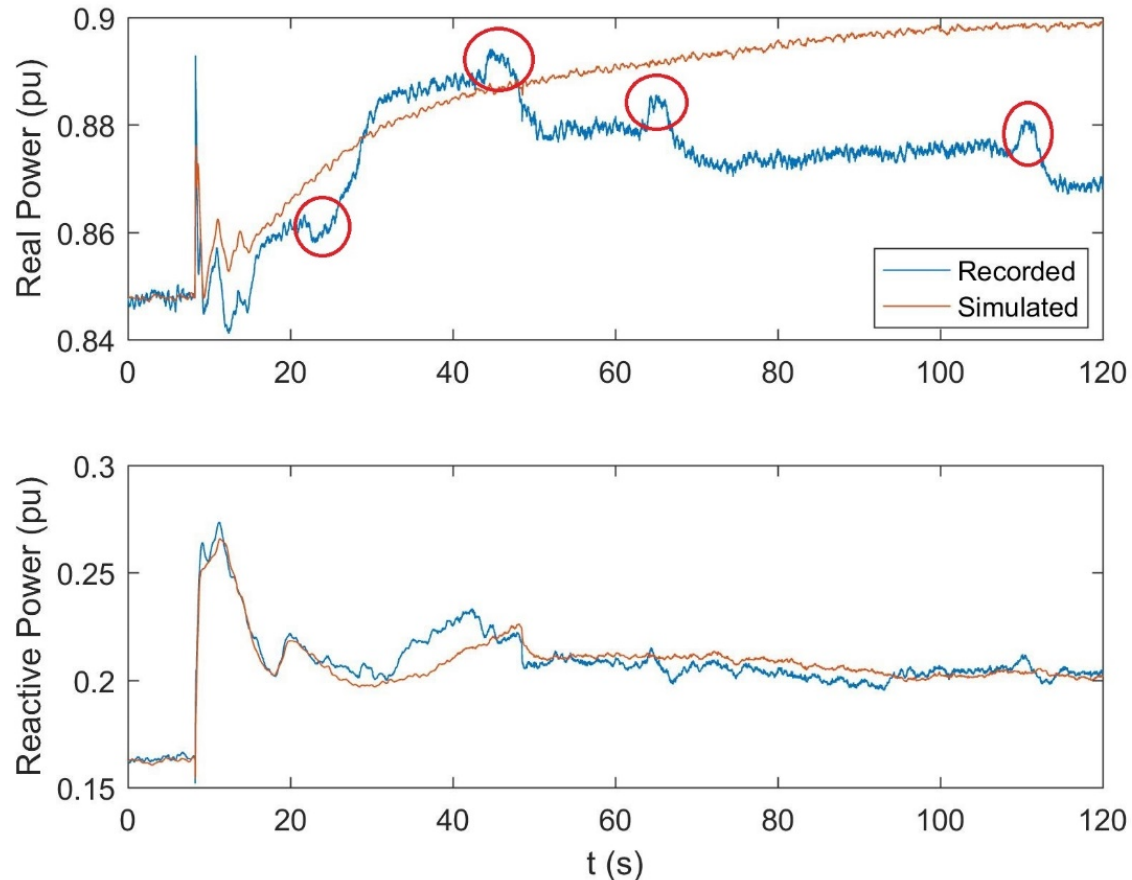
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Playback Simulation

- PMU terminal data injected into simulation, output compared to measured signals
- Other model inputs typically initialized using pre-disturbance data and held constant for duration of simulation



What if inputs change?



- Hydro Unit – real power clearly shows response to reference power change

Parametric Input Estimation

- Absent plant-level measurements of reference inputs, need to estimate them to match simulation conditions to reality

Plant Dynamics (discretized)

$$x_{k+1} = f_d(x_k, u_k, \theta)$$

$$y_k = g_d(x_k, u_k, \theta)$$

Input Vector

$$u_k = \begin{bmatrix} V_k \\ f_k \\ V_{ref,k} \\ P_{ref,k} \end{bmatrix}$$

Parameter Estimation

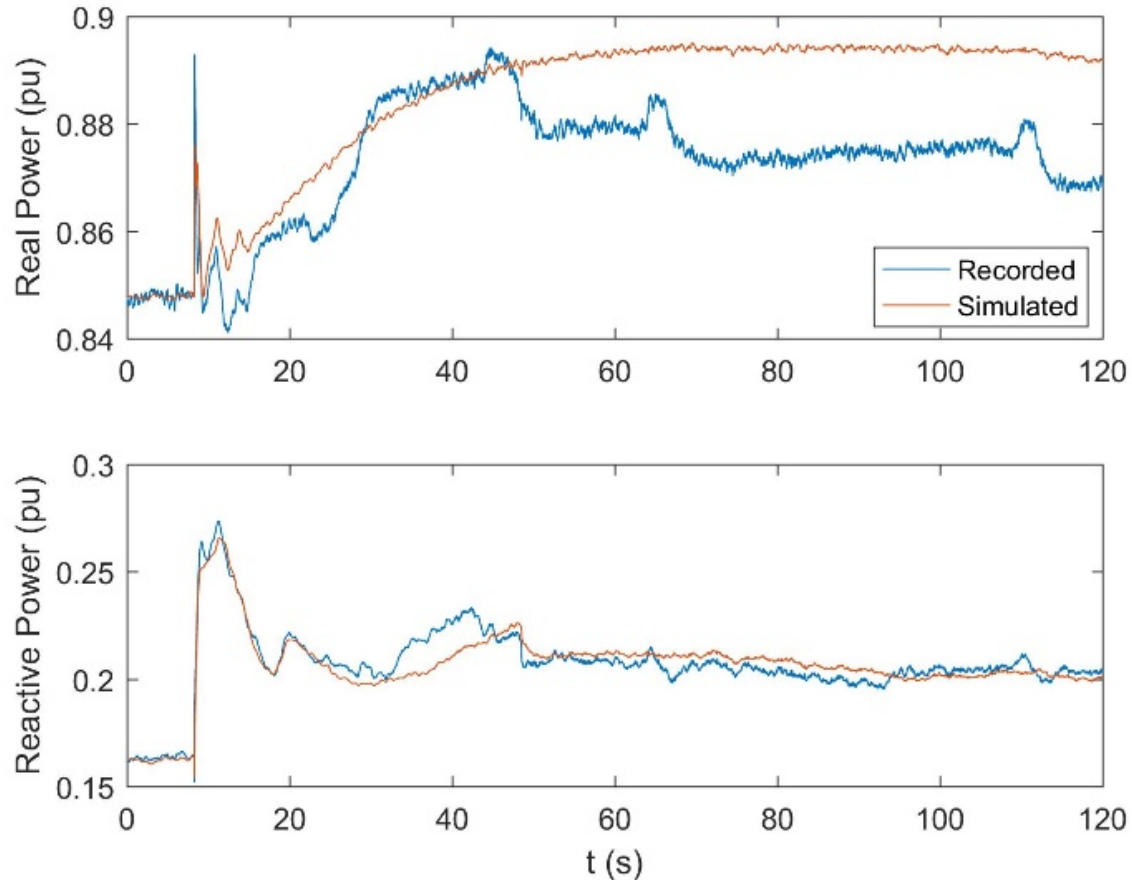
$$V(\theta) = \frac{1}{2} \sum_{k=1}^N (\bar{y}_k - y_k(\theta))^2$$

Estimate Input Function

- Treat reference power as a step function and estimate amplitude and step time along with model params

$$P_{ref,k+1} = P_{ref,k} + \theta_1 \delta(k - \theta_2)$$

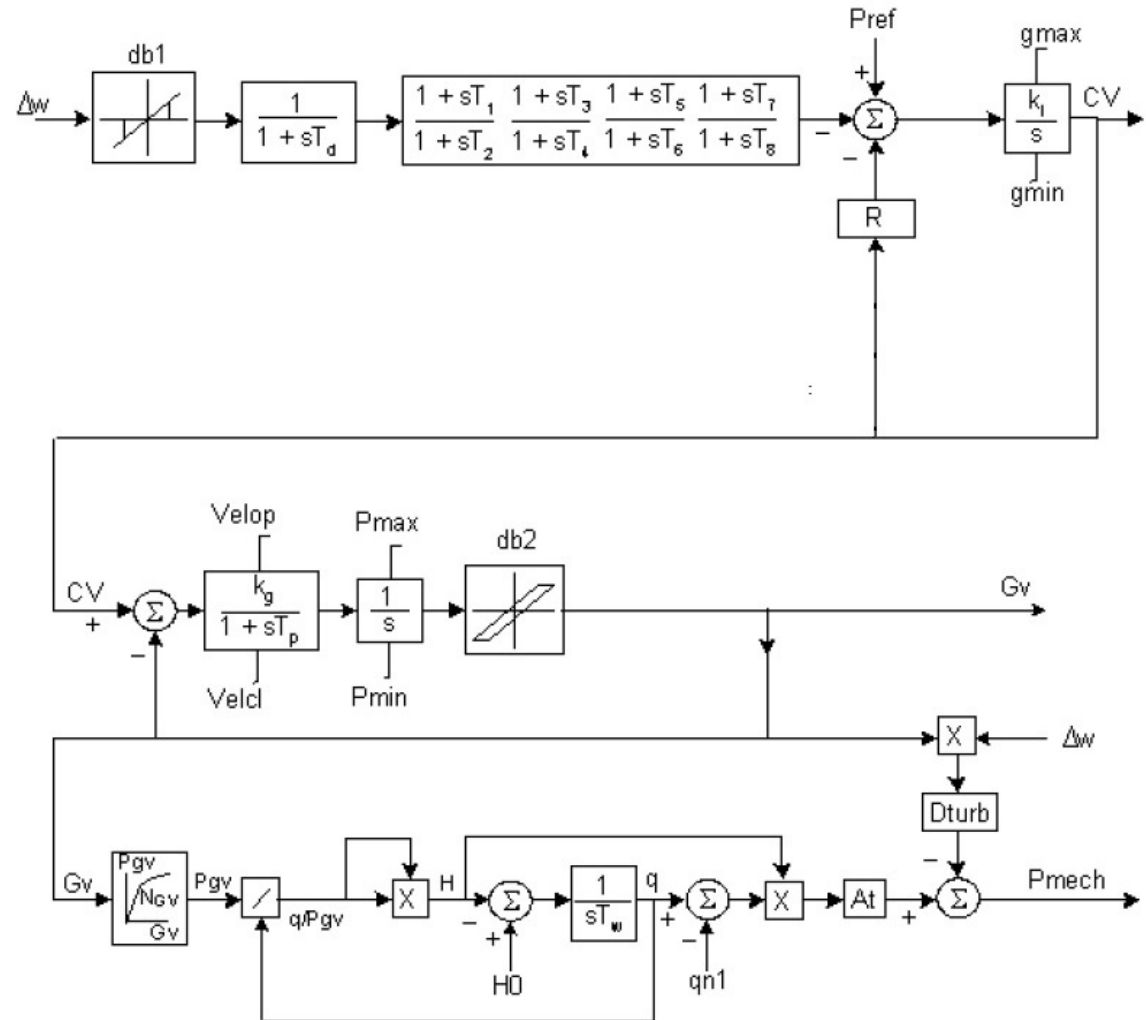
A Case Study



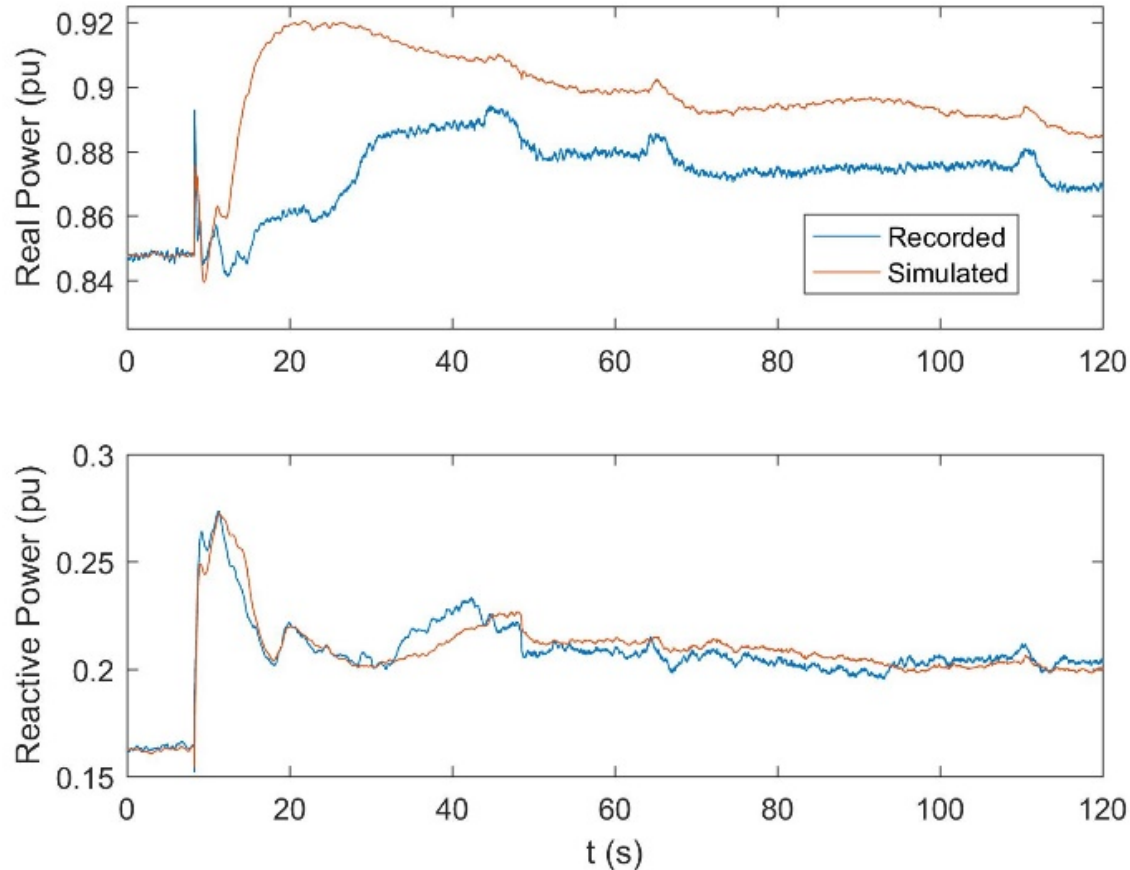
- Attempted to add reference power steps at relevant points – response to them is extremely slow

Turbine Governor Model (hygovr)

- Bottleneck is upper right feedback loop - time constant is 40 seconds

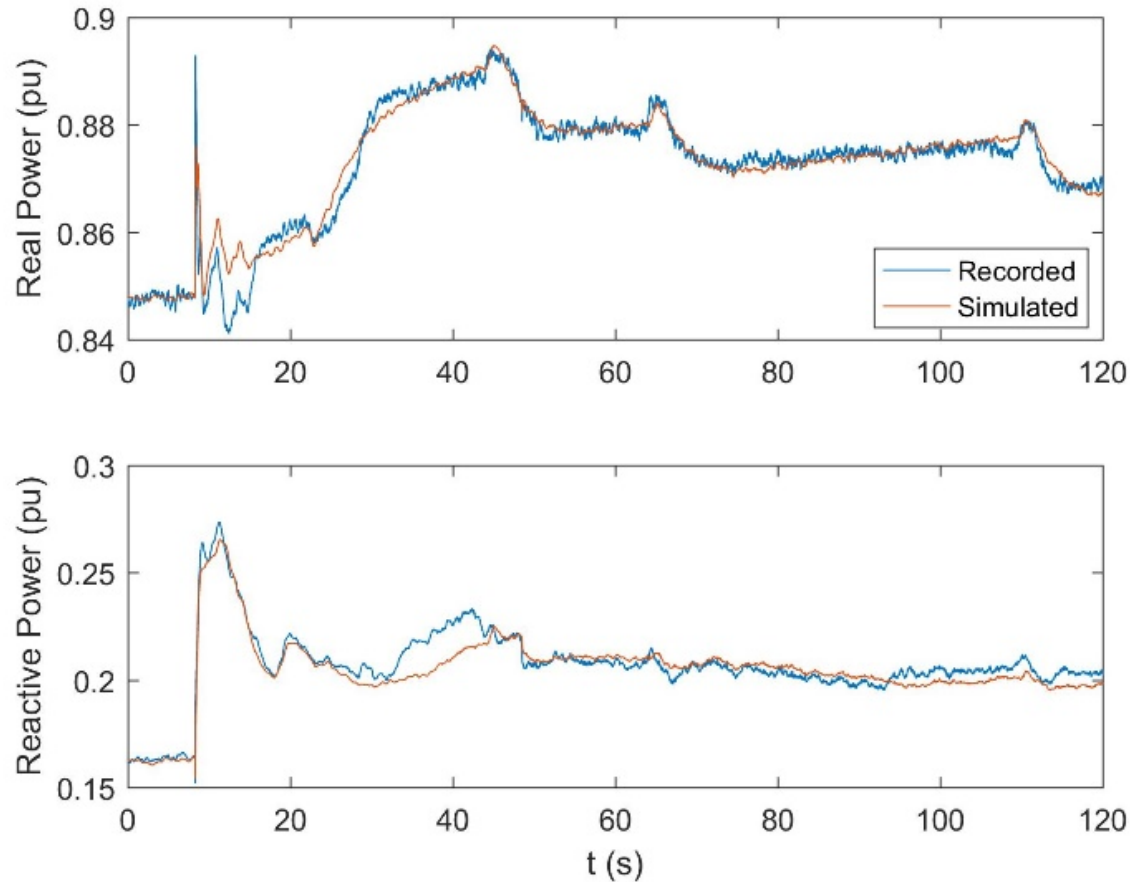


Case Study cont.



- Increased speed of integral loop, but response to frequency deviation now too fast.

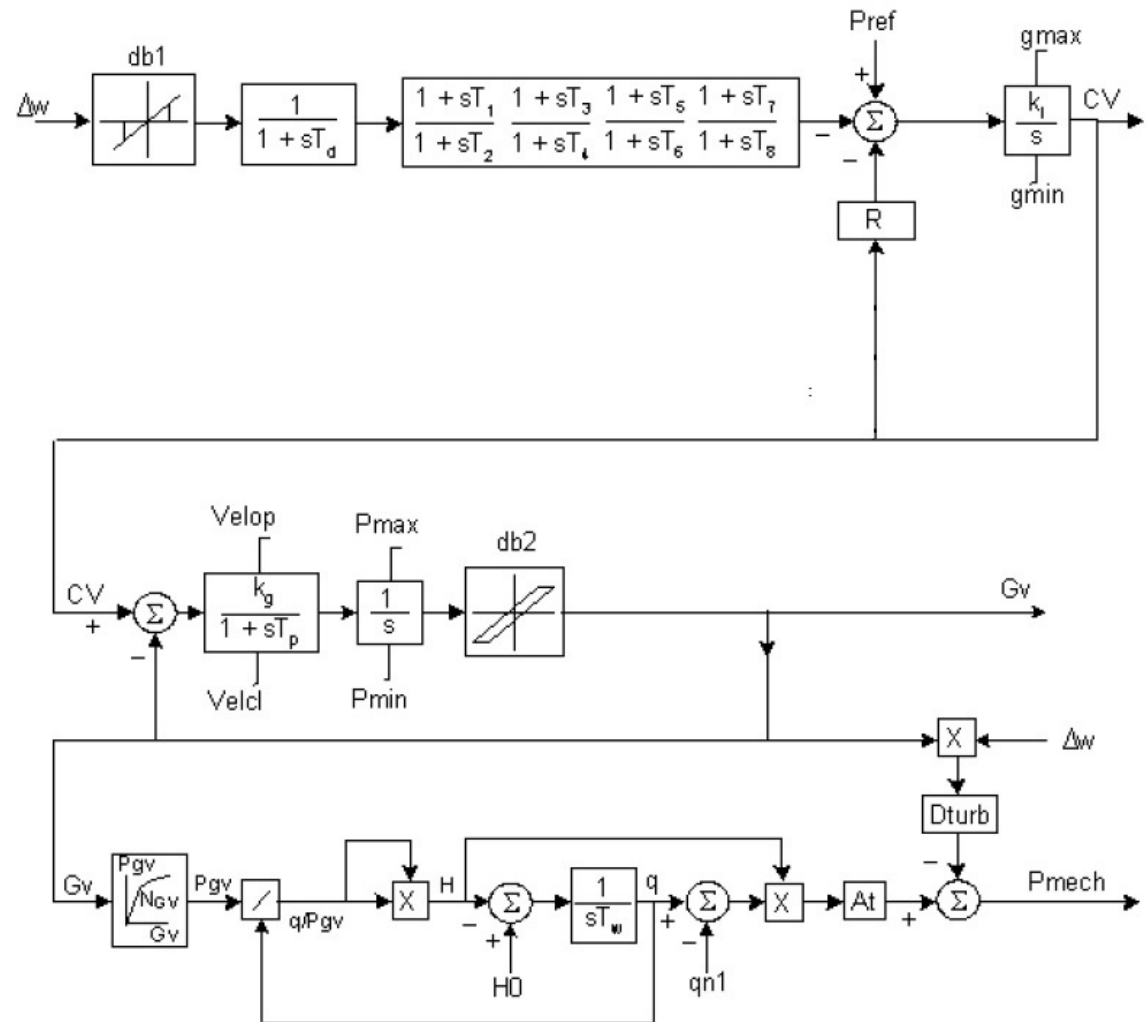
Case Study cont.



- Simultaneously estimated input parameters, T_d and K_I

Summary

- Frequency deviation still needs a dominant time constant of ~40 seconds, must come in path before sum
- Could not have learned this from any simulation with fixed P_{ref}



Conclusions/Future Work

- Narrow view: Input estimation allows for the use of events with changing reference inputs. Value is twofold:
 1. More events can be used for validation.
 2. New **types** of events can be used, which may excite the model in ways that may expose model problems that cannot be otherwise seen.
- Broad view: Moving toward a framework where every PMU data point can be used to inform the validity of the model. Clearly, input estimation is a key component because for most plants, unmeasurable quantities have an effect on the output of the simulation model.

Extra Slide

